



LS800 Series

Flux vector Drive

Flux Sensorless & Open · Closed loop



Comply with:

- Environmentally-friendly technology
- Power-saving technology
- Innovative technology



We were established in 1985. Our factory is located at New Taipei City, Taiwan, For many years, we have been specialized in manufacturing AC vector inverter, DC brushless servo actuator, braking unit and periphery equipment, etc. with excellent quality and price, and also our products have been sold all round the world. In 2002, we passed and were recognized by the international quality standard certification ISO9001:2000, which showed our products with much more improved quality and fulfilled our promises and trusts to our customers.

LS800 series is a series of more than perfect actuators. LS800 series adopts the magnetic flux current control principle with the advanced high technology "direct field conduction" to exactly estimate the magnetic flux and also adopts DSP software and hardware to process the engineering calculation for the output conversion of best rotational torque effect. LS800 series is applied to the control in precision and complex industries and is used in such as AC induced servo motors, crane equipments, high speed elevators, proportional synchronous operational control, fixed current and fixed rotational torque control, fixed tension control and the control of general induced electrical machines.

LS800 Series

Flux vector inverters

VF, VF+PG feedback, Sensorless control, Flux vector control Voltage Range: 200V~240V 1P/3P 380V~460V 3P

Capacity Range: 0.4KW~400KW



LS AC input reactor

Voltage Range: 200V~260V 1P/3P

380V~460V 3P

Capacity Range: 0.4KW~400KW



LSBR Series — Brake unit

Voltage Range: 200V~230V

380V~460V

Capacity Range: 0.4KW~400KW





LS AC ouput reactor

Voltage Range: 200V~260V 3P

380V~460V 3P

Capacity Range: 0.4KW~400KW



High efficiency DR Modular units

Power specifications: 3200w/4600w/6200w Resistance impedance : $6\Omega \sim 80\Omega$

High security / Small volume,

Serial/ parallel connected to spread

Increase wattage capacity



LS DC Bus choke

Voltage Range: DC 200V~800V

Capacity Range: 0.4KW~400KW



LSBR Series - Brake resistors

Voltage Range: 100W~10KW

Resistance : $1\Omega \sim 500\Omega$



EMI Filter

Voltage Range: 200V~260V 1P/3P 380V~460V 3P

Capacity Range:

0.4KW~400KW



LS — operate keypad with exterior cable

Specification:

0.5m, 1.0m, 1.5m, 2m, 3m, 4m, 5m, 6m



Exterior cable with operation box



LS800 Model extension cable with operate keypad

EMI/RFI Noise filter core

Filter frequency range: 150KHz to 30MHz Suitable for LS Series power input / Output



Model: Feedback cards PG-AB2



RS232 to RS485 interface

The encoder reduce

pulse signal board

Maximum reduce pulse range 64K

Suitable for use in elevator of PLC



Model:PG-AB2-1

USB Adapter

Encoder signal conversion Board

Model:PG-XY2 Input: Push Pull or Open Collector Output: Line Driver



Encoder signal board

Maximum receive Pulse 300KHz



Voltage signal conversion Board

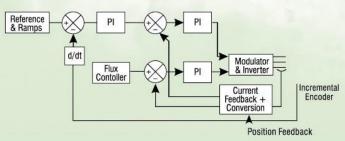
Input: DC 20V~40V

Output: DC 0~5V Or DC 0~10V

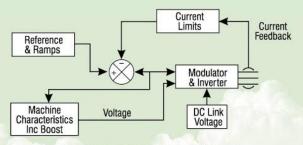


5 operational control modes

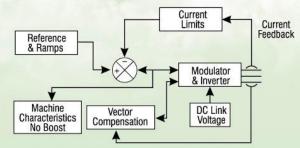
- ◆ Sine wave V/F vector control
- Sine wave V/F vector closed-loop control and closed-loop speed PI adjustment
- ◆ Sine wave V/F sensorless vector control
- Flux vector closed-loop control and closed-loop speed PI adjustment
- Flux vector sensorless control and sensorless speed PI adjustment



Magnetic flux current vector closed-loop control mode



Open loop V/F vector control mode



Flux vector sensorless control mode

International standard communication protocol

- ◆ Built-in RS485 digital operator format
- International standard Modbus Protocol RS485 communication format
- ◆ Applies to man-machine interface and graphics control software
- Offers customized software which:
 - Can use PC to simulate digital operator format control for human-interface operation and instant showing function introduction
 - With RS485 Modbus format, can use PC, PLC, etc. to quickly search, monitor, set, and modify the parameter groups, etc.
 - Before the monitor, can perform saving N sets of parameter groups and multi-machine control, monitoring with automatic synchronous status, etc.
 - Data can be converted into graphics.

RS485/Mod bus Communication Monitoring Tool Parameter Table Command Tools

Built-in Multi-Function I/O interfaces

- 8 sets of Digital-In can perform multi-function compilation
- 3 sets of Digital-Out can perform multi-function compilation
- ◆ 2 sets of Analog-In, 1 set of current signal input
- ◆ 2 sets of Analog-Out can perform multi-function compilation
- 2 sets of Relay can perform multi-function compilation
- ♦ 8 sets of Di and 3 sets of Do can perform Sink and Source in convertible mode control
- ◆ Offering DC24V/200mA for the use of digital terminals

Built-in special practical functions

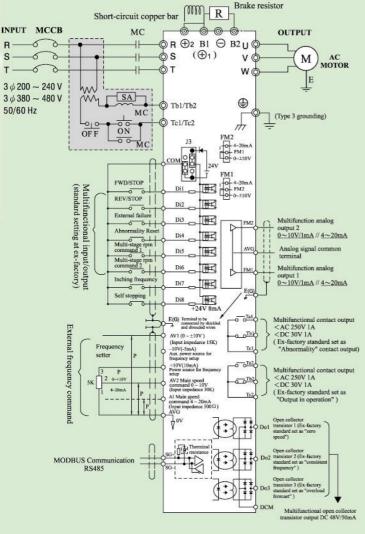
- With digital operator, can perform duplication function and parameter saving function
- ◆ Auto-Tune parameter of motors with precision
- Can input parameters automatically or manually
- ◆ Speed errors within ± 1 r.p.m
- In Standstill Position, rotational torque output 100% in speed zero
- ◆ 2 sets of multi-function PID setting
- 16 sets of speed, 8 for PLC compilation and the other 8 for terminal compilation
- 1 set of multi-function Counter function
- High function PID water pump special-purpose

- Built-in intelligent multi-functional parameter group specialized for water pump
- ◆ Can perform 4 quadrant rotational torque control
- ◆ Can perform fixed current and fixed rotational torque, and fixed tension control
- Speed and rotational torque commands are set and controlled by VR individually
- ◆ S curve, linear curve and V/F curve
- ◆ Slip and rotational torque are compensated automatically
- ◆ AVR automatic voltage regulator control
- ◆ Power saving control system with high efficiency
- Can be adjustment for speed PI control

Multi-function compiler feedback card

- ◆ Response frequency can accept 300KHz to its maximum 400KHz
- ◆ Can perform impulse to monitor input and output
- ◆ Can perform Master and Slave for multi-machine control
- ◆ Applicable for encoder of push pull and line drive signal control

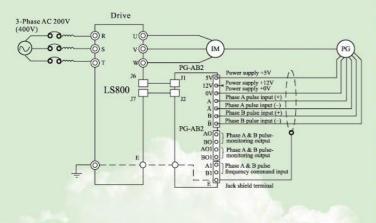
Control Circuit Wiring Diagram (V.2.32)



Schedule of Control Terminal Function (V.2.32)

	rminal Mark	Terminal Designation	Description										
7	Di1	Forward rotation command	Forward revolution when Di1-COM is ON; and st	op, OFF									
Tulti-	Di2	Reverse rotation command	Reversal revolution when Di2-COM is ON; and stop, OFF										
Multi-function Input Terminals	Di3	Input in case of external Abnormality(NC)	AC Drive trips off to stop when external abnormality signal is ON (Err 29)										
tion	Di4	Abnormality reset	Di4 ON releases the status imposed and maintained by the circuit protection action against failure.										
Į.	Di5	Multi-section command 1	To execute four-section speed control with binary	2D:4									
I II	Di6	Multi-section command 2	To execute four-section speed control with binary	ZDIL.									
em	Di7	Jog inching frequency	To execute the inching frequency operation when	enabled ON.									
Ting:	Di8	Free-run	When activated (ON), the drive immediately stops	s outputting.									
ıls	СОМ	Digital Input common terminal	The multi-function input terminals of the commor	terminal									
Α	+10V	Source for F setup	Source output DC +10V for frequency setup (max allowed)	imal 10mA									
nalo	-10V	Negative source for F setup	Auxiliary negative source output DC -10V for F s 5mA allowed)	etup (maximal -									
Analog frequency setup	AVG	Common terminals for F setup	Common reference potential terminal for F setup input signals (terminal AV1. AV2. AI)										
quen	AV1	Analog voltage F command	With input voltage at DC 0~ \pm 10V (or DC 0~ \pm 10V), the input impedance is 15k Ω										
cy se	AV2	Analog voltage F command	With input voltage at DC 0~+10V, the input impedance is $30k\Omega$										
th th	AI	Analogy current F command	With input current at DC 4~20mA, the input impedance is $500k\Omega$ (or DC 0~+10V, $30k\Omega$)										
	DO1	Zero-Speed detected	ON in stop status or below zero-speed level										
	DO2	Consistent F	ON when the output F at any setting is over the detected F.										
	DO3	Overload forecast	On when the drive detection output is over the OL level										
Mul	DCM	Digital output common terminal	The multi-function output terminals of the common terminal										
Multi-function Output Terminals	Ta1	Output in normality (NC)	la and lb contacts function to output when the abnormality protection mechanism of the drive is activated.										
ıcti	Tb1	Tal Tbl	*Ta1-Tc1 is ON in case of abnormality Contact	Contact Capacity:									
On O	Tc1	Tcl	*Tb1-Tc1 is OFF in case of abnormality Contact DC 30V 1.										
Outp	Ta2	In Operation	la and lb contacts function to output when the F to output of ac drive is above the value as preset.	o activate the									
H.	Tb2	Ta2 Tb2	*Ta2-Tc2 is ON during operation Contact	Contact Capacity:									
len	Tc2	Tc2	*Tb2-Tc2 is OFF during operation Contact	AC 250V 1A DC 30V 1A									
nina	FM1	Analog output, FM	Multi-function analog monitor 1, DC 0~+10V/ (or 4~20mA)100% FM meter head										
So.	FM2	Analog output, amperage monitor	Multi-function analog monitor 2, DC 0~+10V(or 4~20mA) /100% ac drive rated A.										
	AVG	Analog output common terminal	The pulse frequency (FM) terminal of the common termina										
COM	SG+	RS-485 series com. interface	RS-485 series com. jack, positive end input										
M.	SG	RS-485 series com. interface	RS-485 series com. jack, negative end input										
	Е	Earth cable terminal	Exclusively for the shielded cable to connect the selected earth shielded cable use.										

PG-AB2 Wiring Diagram



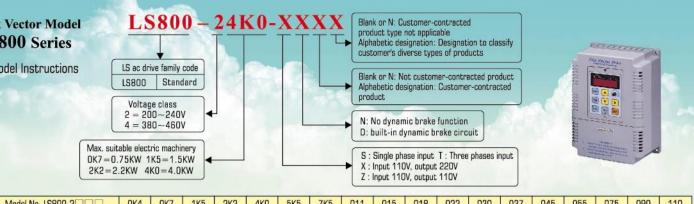
PG-AB2 Terminals Specification

Terminal Mark	Description	Specificatio
E	Shielded cable connection ground terminal	
A	Phase A pulse input (+)	Adaptable to Line Driver, Encoder with 5V or 12V source of complementary and open collector transistor, A, B. Phase
Ā	Phase A pulse input (-)	signal output. **Maximal response frequency 300 KHz.
В	Phase B pulse input (+)	¾ If open collector transistor type of input is used, connect
B	Phase B pulse input (-)	Phase A and Phase B terminals to source terminals of 12V encoder.
AO	Phase A pulse monitor output	The maximal for Phase A and Phase B open collector transistor output is DC 5V/30mA.
ВО	Phase B pulse monitor output	Maximal response frequency 300 KHz
5V		DC +5V (± 5%), 200mA(max.)
12V	Pulse generator dedicated source	DC +12V (± 5%), 200mA (max.)
0V	**/	DC 0V (+5V and +12V share the common grounding terminal)
A1	Phase A pulse frequency command input	For Phase A and Phase B, the input is done by open collector transistor type (0-300 KHz). (Select J3 according to the
B1	Phase B pulse frequency	specification.
AO1	Phase A pulse frequency command monitor output	Phase A and Phase B open collector transistor output, DC 5V/30mA (max.)
BO1	Phase B pulse frequency command monitor output	Maximal response frequency 300 KHz

Flux Vector Model LS800 Series

Model Instructions

Cooling fan



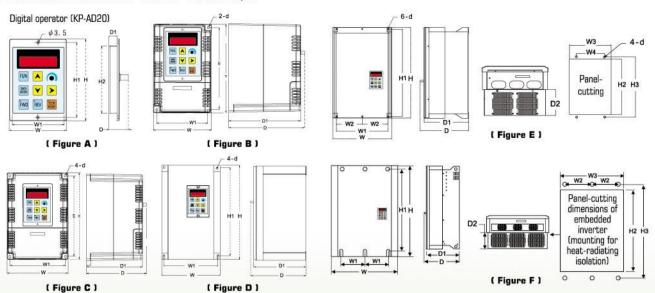


22	Model No. LS800-2		OK4	0K7	1	1K5	2K2	4K0	5K5	7K	5	011	015	018	022	030	0	137	045	0	55	075	090	1	10
ğ	Applicable motor power (KW)		0.4	0.75	1	1.5	2.2	4.0	5.5	7.5	5	11	15	18.5	22	30	;	37	45	5	5	75	90	1	10
Se	Α	pplicable motor power (HP)	0.5	1		2	3	5	7.5	10	ו	15	20	25	30	40		50	60	7	5	100	125	1	50
		Rated output capacity (KVA)	1.5	2.0	3	3.1	5.2	7.3	10.4	14.	.0	21.0	28.0	34	42	54		69	79	9	6	125	146	1/	89
8	0	Continuous rated current (A)	3.7	5	7	7.5	12.5	17.5	25	34	4	50	68	82	100	130	1	65	190	23	30	300	350	4	55
eci	Output	Max. output voltage (V)									3-pt	hase co	orrespo	nding in	ut volt	age									
i da	17	Output frequency range (Hz)		0.0~400.0Hz														10	- 22						
9		Carrier frequency (Hz)		16KHZ 12KHZ 10KHZ 8KHZ 6KHZ												IZ	5KH	Z 3K	KHZ						
ਲ	Po	Input voltage, frequency								3-р	hase	power	supply	200V~	240V 5	0/60H	Z								
	Power supply	Tolerance for voltage fluctuation of power supply		- 15%~+10%(170V~265Vac)																					
Tolerance for frequency fluctuation of power supply ±8% (47HZ~64.8HZ)																									
		Cooling fan	Forced fan																						
			D-10000				CONTRACTOR	-1	1						11										
4	_	Model No. LS800-4			-	-	K5 7k			E CONTRACTOR OF THE PARTY OF TH	022	030	17.0	45 055					160	185	220	280			400
9	-	oplicable motor power (KW)	0.75				5.5 7.	-	_	18.5	22	30		5 55	75		_		160		220			-	400
se	Α	pplicable motor power (HP)	1		_		7.5 1		20	25	30	40		0 75	100					250	300	375			540
Ties:		Rated output capacity (KVA)	_	4.0 6				.0 20.0	-	34.3	40	54		104	_	_	_	_	\rightarrow	279	363	418	-		598
8	0	Continuous rated current (A)	3.7	5 7	.5 ′	10	14 17	.5 25	38	43	50	68		00 130			230	275	300	350	455	525	600	680	750
ec.	Output	Max. output voltage (V)		3-phase corre									orrespo	nding input voltage										_	
fice	7	Output frequency range (Hz)											0.0~4	100.0Hz											
킇		Carrier frequency (Hz)		16KHZ			12k	ΉZ	1	OKHZ			8KHZ	6	KHZ	5KH	Z	4Kł	HZ	3KF	ΗZ	2KHZ			
S.	Por	Input voltage, frequency				377				3-pl	nase (power	supply	380V~	480V	50/60H	łΖ		(2)			17			
	Power su	Tolerance for voltage fluctuation of power supply									-1	15%~	+10%	(323V~	-528Va	ic)									
	supply	Tolerance for frequency fluctuation of power supply										±8	% (47H	Z∼64.8	3HZ)										
		0 !											F	1.6											

Forced fan

	Control method	Sine wave SVPWM, 2-phase or 3-phase modulation, switching frequency 1K~16KHZ adjustable, five control modes — V/F × V/F + closed loop × V/F sensorless > Flux vector control + closed loop > Flux vector sensorless.
	Max. output frequency	0.0~400.0Hz
	Frequency precision (temperature fluctuation)	Digital signal $\pm 0.1\%$ (-10°C $\sim +40$ °C) , Analog signal $\pm 0.1\%$ (25°C ± 10 °C)
	Precision for frequency setup	Digital signal : 0.1Hz(0.0∼400.00Hz) , Analog signal : 0.1/60.0Hz
	Precision for speed regulation	Voltage sensor-less vector $:>$ 10Hz $:=\pm1.0~\%$ \cdot V/F $:\pm3.0\%\sim5.0\%$
Control	Acceleration / deceleration time	$0.0 \sim 30000$ (seconds), acceleration/deceleration can be governed by 4 types of adjustment respectively and portioned out into 16 stages of speed for application.
<u>o</u>	Control functions	40 display functions, 8 rpm command sources, Torque Limit, zero-speed vector control, variable and constant torque control, selection of sink and source, upper & lower frequency setup, AVR function, S-curve, multiplexing input, output terminal control, 16 preset stages for speed regulation, hopping frequency, Auto-Tuning, detection & measurement of static and dynamic motor parameters, , slip compensation, Torque compensation, dual PID functions, DC brake at on/off, multistage operation functions, RS485/Modbus communication, automatic operation function, energy-saving operation, built-in copy function.
	Signal for frequency setup	DC O $\sim \pm 10 \mathrm{V}$, DC O $\sim +10 \mathrm{V}$, 4 \sim 20mA, puls command input by PG card
	Brake torque	20% approximately, 125% with brake controller mounted.
	Control functions	Digital operation panel, speed regulation, sensor-less flux control, PID control, multistage speed control, etc.
	Motor protection	Integral electronic thermal relay protections.
	Over-current protection	Will trip at over-current protection to enable a free run of motor when exceeding the 200% rated current
	Overload ability of ac drive	Motor rated output current exceeds the 150%, cumulative time 1 minutes free running stop.
P	Over-voltage protection	Over-voltage level: Vdc > 400V(200V~240Vclass) /Vdc > 800V(380V~480Vclass)
otec	Low-voltage protection	Low-voltage level: Vdc < 180V(200V~240Vclass) / Vdc < 380V(380V~480Vclass)
Protection functions	Power supply protection	Under phase protection for input power supply (equipped for ac drive with a power above 5.5KW), under phase protection for output (equipped for ac drive with a power above 0.4KW)
ncti	Superheating heat radiation fins	Thermal coupler protection $85^{\circ}\text{C} \pm 5^{\circ}\text{C}$
Suc	Stall protection	To protect the device from stall during acceleration/deceleration and operation.
	Grounding protection	To protect electronic circuits.
	Charging indication	Charging indicator will be turned "ON" when the DC voltage of main circuit is over 50V.
	Place used	Indoor places free of corrosion or dusts.
, m	Ambient temperature	-10°C ~ +45°C (Lock wall-mounting model), -10°C ~ +50°C (open model) free of freezing condition
Viro	Storage temperature (Note 1)	-20°C ~ +60°C
Environment	Humidity	Below 95% RH (no condensation condition)
T T	Vibration	20Hz ≤1G, 20 ~ 50Hz 0.2G

Outside Dimension Chart UNIT: m/m



o O	Drawing	Applicable motor capacity		oughing nsions		di		tant ins (mn	1)			Holing dimen	Net weight		Meas ure			
2	No.	(HP)/(KW)	W	Н	D	W1	W2	H1	D1	d	W3	W4	H2	НЗ	D2	(kg)	(kg)	ment
n	A	KP-AD 20	70.9	102	25.8	-	_	93	15.8	3.5	65.3	_	84.5	_	-	0.066	0.072	-
Ď		0.5 / 0.4														1.9		
₽.	ъ	1 / 0.75	114	172	146	101	_	159	136	5.3	-	_	_	_	-		1.9	2
	В	2 / 1.5	114	172	146	101												
	20	3 / 2.2																
]	С	5 / 3.7	152	214	146	137.5	=	200	136	5.3	-	_	=	===	(-)	2.3	2.9	2.7
		7.5 / 5.5	188		180	170 218								460	112	7.2	8.9	
	D	10 / 7.5		300				283	217	7	242	170	445			7.2	8.9	1
		15 / 11														7.3	9	
		20 / 15		458												17	18.6	1.8
		25 / 18.5														17.5	19	
		30 / 22					L.									17.7	19.2	
	E	40 / 30			276								546		140	31	36.2	
		50 / 37	345	563		303	152	545	266	7	337	212		568		31.4	36.6	4.9
		60 / 45	343	202	2.0	505		543	200		201	200	5.10			32.2	37.4	4.2
		75 / 55														33.7	38.9	
	800	100 / 75	88000		322		262				596	440	745	769	158	76.2	91.2	11.6
	F	125 / 90	604	770		525		749.5	312	11						77.4	92.4	
		150 / 110														78.6	93.6	

Drawing No.	Applicable motor capacity		oughing ensions		di	Cons mensio	tant ns (mm	1)	ψ			j, const isions (Net weight	The second second	Meas ure		
5 INU.	(HP)/(KW)	W	H	D	W1	W2	HI	D1	d	W3	W4	H2	H3	D2	(kg)	(kg)	ment
A	KP-AD 20	70.9	102	25.8	-		93	15.8	3.5	65.3	-	84.5	-	-	0.066	0.072	-
D	0.5 / 0.4															1000	
2 5	1 / 0.75		222					12.213	0.0								
D B	2 / 1.5	114	172	146	101	-	159	136	5.3	_	-	_	-2	-	1.4	2	2
ഗ	3 / 2.2																
C	5/3.7	152	214	146	137.5	_	200	136	5.3	-	-	-	-	-	2.3	2.9	2.7
	7.5 / 5.5	188					283	170	7	_	-	K—	 (_	7.2	8.9	1
D	10 / 7.5		300	180	170										7.2	8.9	
5	15 / 11														7.3	9	
ហ	20 / 15	250	458							242	170	445	460		17.6	19	
	25 / 18.5			227	218	-	440	217	7					112	18	19.4	1.8
	30 / 22											443	400	112	18.2	19.6	1.6
in E	40 / 30														18.2	19.6	
L	50 / 37	345		276	303	152	545	266	7				568	140	31.2	36.4	4.9
	60 / 45		563							337	212	546			31.2	36.4	
	75 / 55		303											140	32	37.2	
	100 / 75														33.5	38.7	
	125 / 90														78.3	93.3	
	150 / 110														79.5	94.5	
F	175 / 132	604	770	322	525	262	749.5	312	11	596	440	745	769	158	80.7	95.7	11.6
	200 / 160	604	7,70	522	020	202	1.13.15	212		0.555	10.14	/45	769	150	80.7	95.7	11.0
	250 / 185														81.9	96.9	
	300 / 200														81.9	96.9	
	375 / 280			2.2			Confir	med to	us								
y	425/315, 475/355 Confirmed to us															2	